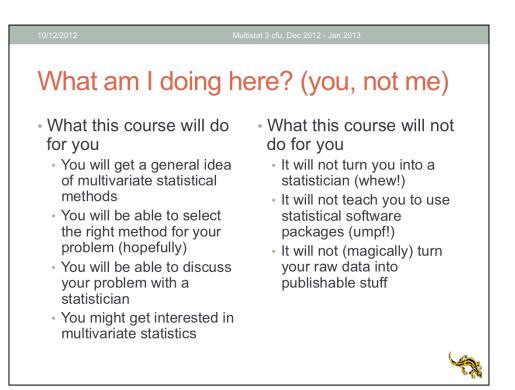


What I cannot teach you: how to look for relevant literature, how to use statistical software

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#### 2/2012

#### ltistat 3 cfu, Dec 2012 - Jan 20

# But then, who are you (me, not you)?



"Cheshire Puss," she began, rather timidly, as she did not at all know whether it would like the name: however, it only grinned a little wider. "Come, it's pleased so far," thought Alice, and she went on, "Would you tell me, please which way I ought to walk from here?"

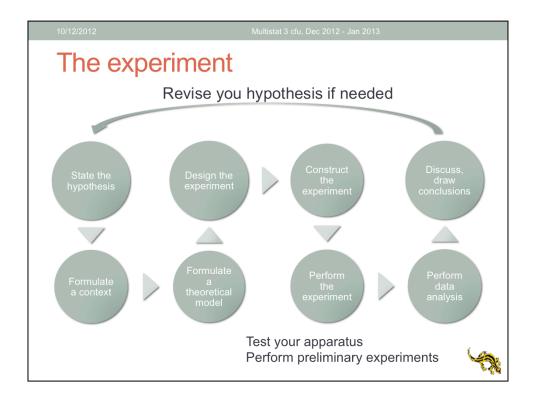
"That depends a good deal on where you want to get to," said the Cat.

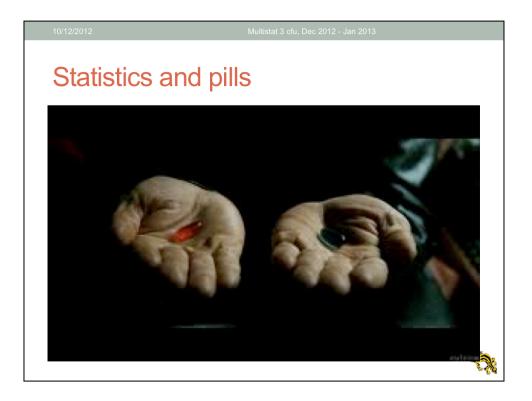
"I don't much care where - " said Alice. "Then it doesn't matter which way you walk," said the Cat.

" - so long as I get somewhere," Alice added as an explanation.

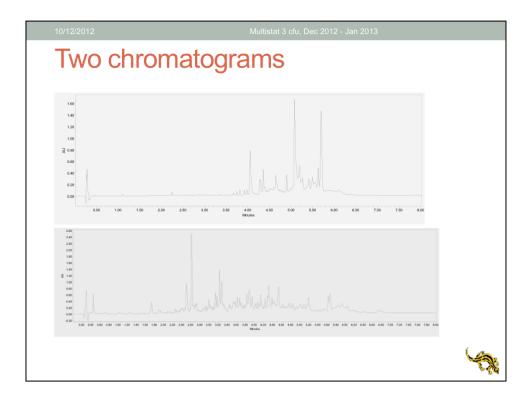
"Oh, you're sure to do that," said the Cat, "if you only walk long enough."

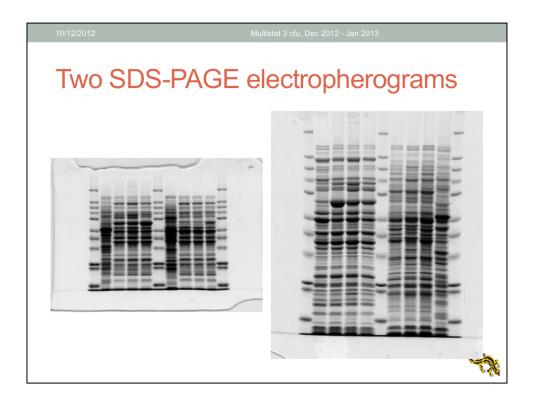


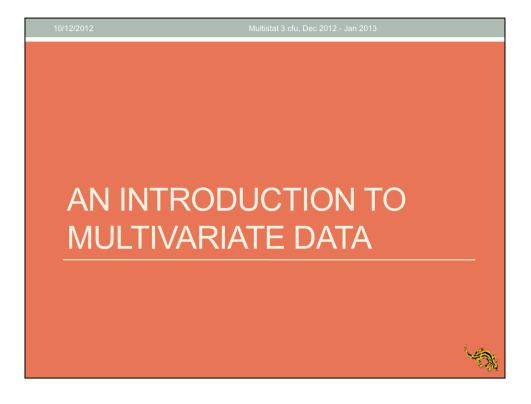


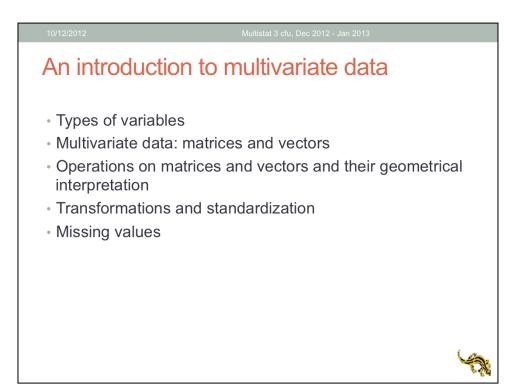


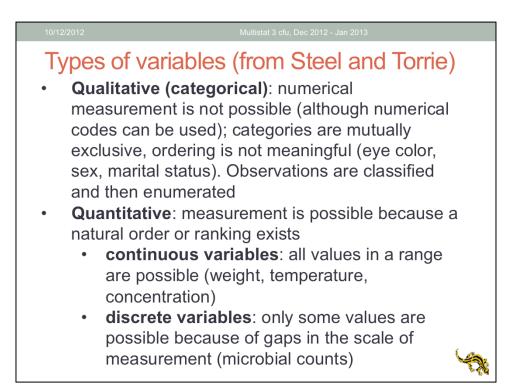
2012 Witistat 3 cdu, Dec 2012 - Jan 2013
Choore) woords of caution
Phere is no cure for a badly planned experiment
Statistical design and analysis should be incorporated in the experiment at the planning stage:
be careful with the set-up of blocks replicates etc.,
use a design appropriate for the scope of your analysis
There is no cure for bad data
be careful with sampling
be (extra) careful when you perform your analyses
never (fully) trust your instruments











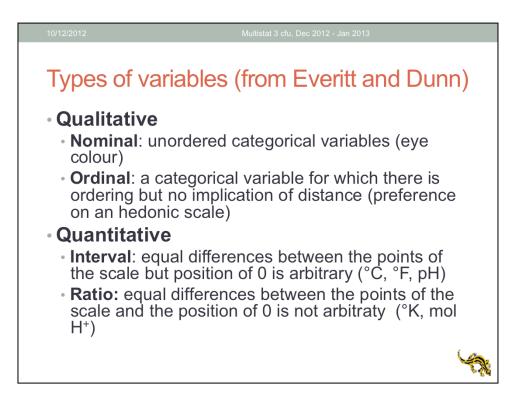
Make examples of types of variables

categorical unordered: eye color, sex, marital status

Categorical with ordering: level of instruction, weight class

Quantitative continuous: weight, temperature (can we really measure on a continuous scale?)

Quantitative discrete: microbial counts



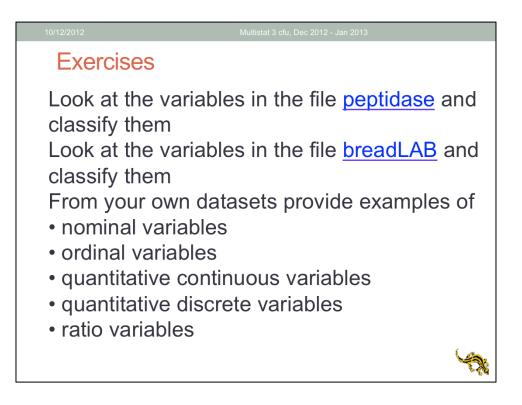
Ordinal variables are frequent in sensory science and psychometics: people may not use a linear scale and distance between points on a scale (i.e. an hedonic scale 0-9) might not be constant

The difference between interval and ratio variables is important: although they both use scales with constant intervals, the fact that the 0 in interval scales is arbitrary has implications in comparing values. For example, temperature in °C is an interval scale with an arbitrary 0, while temperature in °K is a ratio scale. A body at 40°C is not twice as hot as a body at 20°C as can be easily seen by converting in °K.

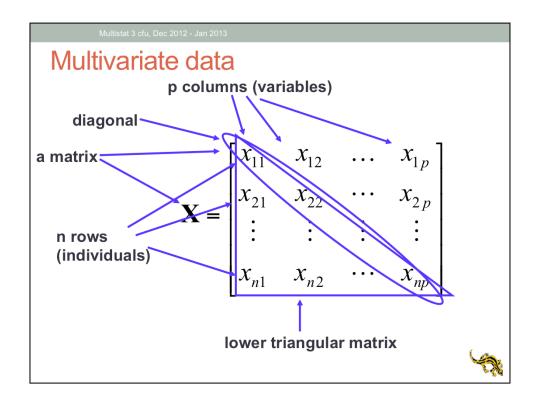
OK to compute	Nominal	Ordinal	Interval	Ratio
Frequency distribution	Υ	Υ	Υ	Υ
Median and percentiles	Ν	Υ	Υ	Υ
Add or subtract	Ν	Ν	Y	Υ
Mean, standard deviation, standard error of the mean	Ν	Ν	Y	Y
Ratio or coefficient of variation	Ν	Ν	Ν	Υ

From http://www.graphpad.com

**N** 



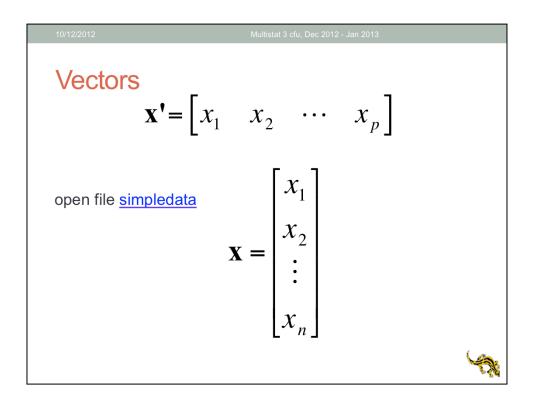
Link Systat or Excel data files



A data matrix may often include both categorical and quantitative variables, although most often only the latter are used

Trace of a matrix is the sum of its diagonal elements. Addressing of the elements in the matrix is relevant, since a matrix is an ordered table of elements. Usually the index i is used for rows and j for columns.

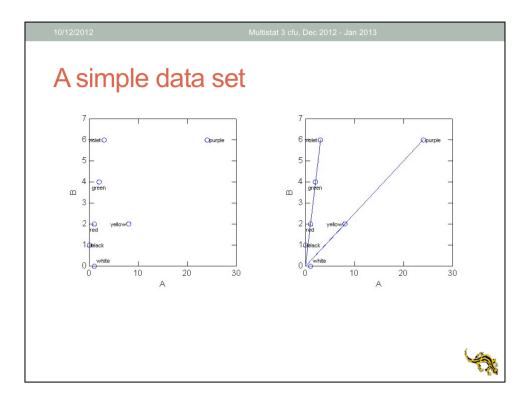
A symmetric matrix is a square matrix which is equal to its transpose: distance and similarity matrices are usually symmetric

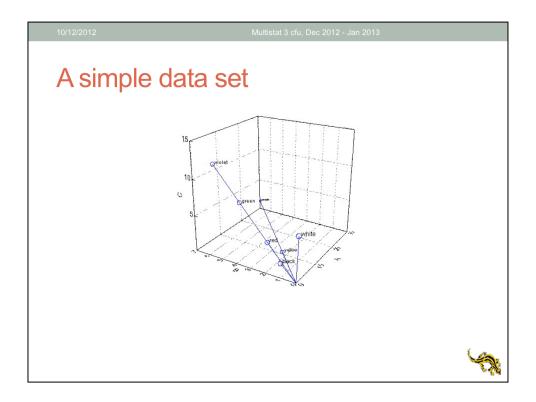


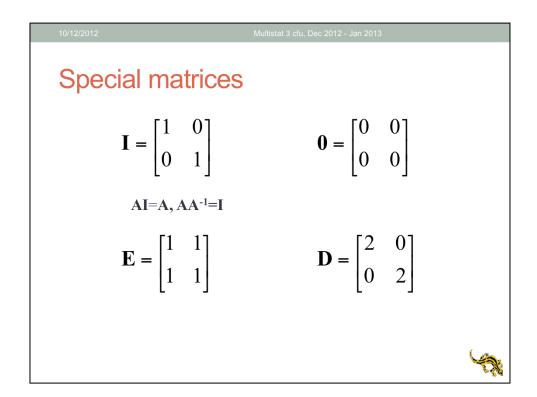
A row vector specifies coordinates in an Euclidean space with p dimensions, i.e. specifies the value of all variables for a single observation. x' is a trasposed vector (usually the notation is used to indicate row vectors anyway). A matrix is actually made by one or more row vectors (or column vectors). Therefore transposition of vectors or matrices is simply exchanging rows for columns (first row becomes first column and so on and a nxp matrix becomes a pxn matrix)

The rank of a matrix is the number of the row vectors which are linearly independent. A matrix is full rank if all the row vectors are linearly independent

10/12/2012		Multistat 3 cfu, Dec	: 2012 - Jan 2013	
A simpl	e datase	et		
A	B 0 1 2 8 24 3	C 1 2 0 4 2 6 6	LABEL\$ 2 black 4 red 6 white 8 green 1 yellow 3 purple 12 violet	
				5







Special matrices:

I (identity) all 0 except the diagonal, (1). It plays the same role as the number 1 in multiplication in arithmetics

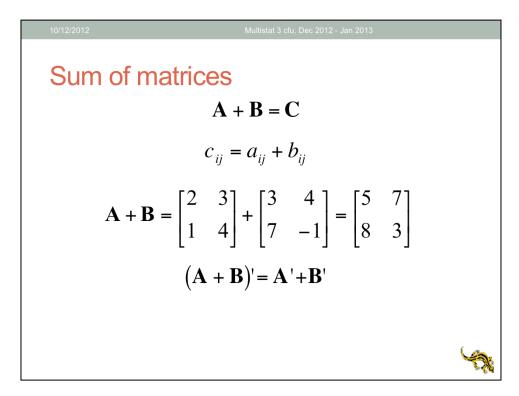
0 (null) all elements are 0,

E, all elements are 1.

A square matrix which is equal to its transposed matrix is symmetrical.

Diagonal matrix, all elements are 0 except the diagonal.

The inverse of a matrix is the matrix which, when multiplied for the original matrix, gives the matrix I. Multiplication by the inverse of a matrix is the equivalent of division



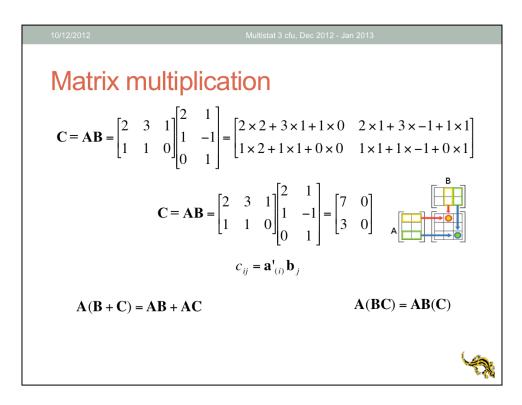
Sum and difference of matrices can be carried out only if the two matries have the same dimensions and the results is the ordered sum (difference) of elements

The following properties hold:

Commutative A+B=B+A

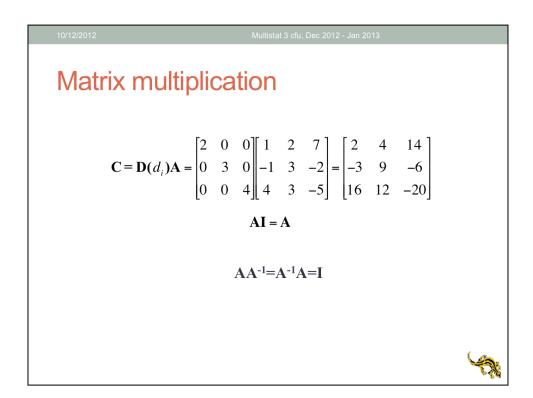
Associative A+(B+C)=(A+B)+C

A-(B-C)=(A-B)+C



**Scalar multiplication**: all elements are multiplied by a scalar. Matix multiplication is possible only if the number of columns n of the first matrix is equal to the number of rows of the second matrix. Commutative property does not apply to matrix multiplication, whiel associative (ABC=(AB) C) and distributive (A(B+C)=AB+AC) properties apply. If two matrices have dimensions (m,n) and (n,p) the result of their multiplication has dimensions (m,p). The product of any matrix by the identity matrix (I) is the matrix itself. The internal product of two vectors is a scalar x' x which is the sum of squares of the x elements of the vector and also is the square of the distance of the point represented by the vector from the origin. While if holds (AB)' =B' A' in general BA=AB does not hold

The image is from: http://en.wikipedia.org/wiki/Matrix\_(mathematics)



Premultiplication of a matrix by a diagonal matrix gives a second matrix in which each row of the second matrix is multiplied by the corresponding diagonal element of the first matrix. if you premultiply by a diagonal matrix, the rows of the matrix are multiplied by the element of the diagonal; if you postmultiply, the columns are multiplied

The inverse B of a square matrix A is a matrix such as:

AB=BA=I

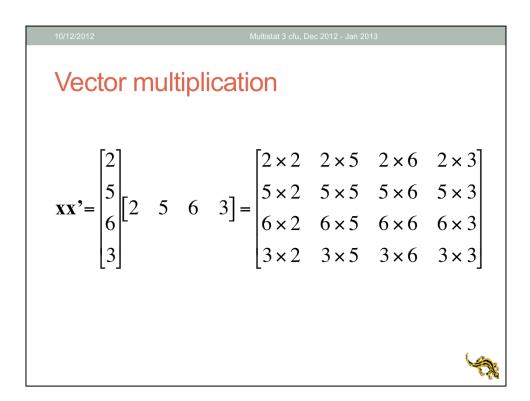
A matrix is singular or degenerate if it cannot be inverted; this happens if and only if the determinant is 0.

A matrix is invertible only if it is full rank.

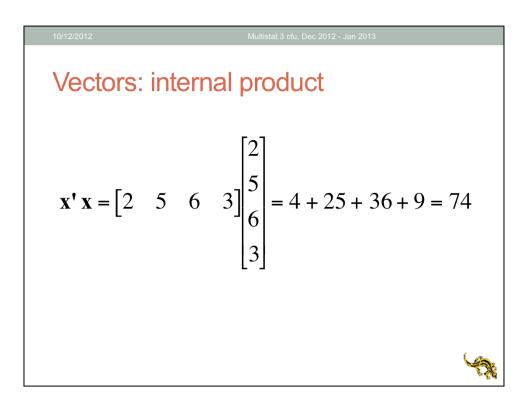
10/12/2012 Wuldistal 3 cfu, Dec 2012 - Jan 2013  
**Vectors: scalar product**  

$$\mathbf{x}^{*} = \begin{bmatrix} x_{1} & x_{2} & \cdots & x_{p} \end{bmatrix}$$
  
 $\mathbf{cx}^{*} = \begin{bmatrix} cx_{1} & cx_{2} & \cdots & cx_{p} \end{bmatrix}$ 

The scale of the vector changes by multiplication by the scalar c. Scalar multiplication of a matrix works exactly in the same way. From an Euclidean point of view, multiplication of a vector by a scalar changes its length by the factor c.



The matrix obtained by this product is the SSCP (sum of squares and cross products) matrix, a simmetrical matrix.

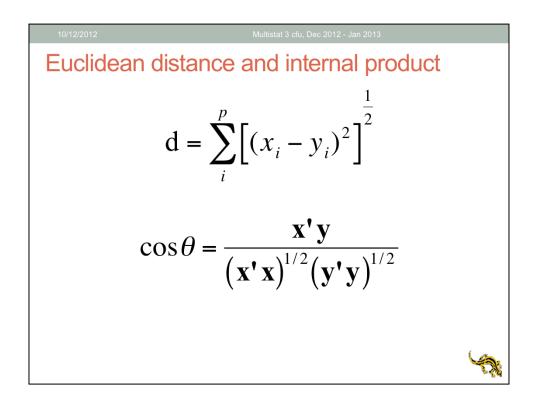


It is the sum of squares of the vector. By convention vectors are written as row vectors. Column vectors are obtained by transposing row vectors

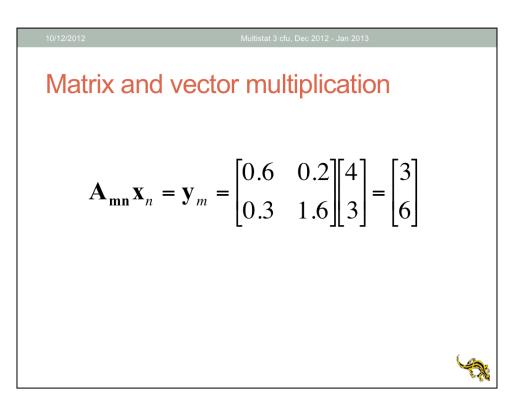
10/12/2012	Multistat 3 cfu, Dec 2012 - Jan 2013							
Multiplication and linear transformation								
$\begin{array}{c} \text{Vertical shear with m=1.25.} \\ \begin{bmatrix} 1 & 1.25 \\ 0 & 1 \end{bmatrix} \end{array}$	Horizontal flip $ \begin{bmatrix} -1 & 0 \\ 0 & 1 \end{bmatrix} $	Squeeze mapping with r=1.5 $\begin{bmatrix} 3/2 & 0 \\ 0 & 2/3 \end{bmatrix}$	Scaling by a factor of 1.5 $\begin{bmatrix} 3/2 & 0\\ 0 & 3/2 \end{bmatrix}$	$\label{eq:relation} \begin{array}{l} \mbox{Rotation by n/6 = 30^{\circ}} \\ \mbox{\left[} \cos(\pi/6) & -\sin(\pi/6) \\ \sin(\pi/6) & \cos(\pi/6) \end{array} \end{array} \right]$				
				5				

Image from http://en.wikipedia.org/wiki/Matrix\_(mathematics).

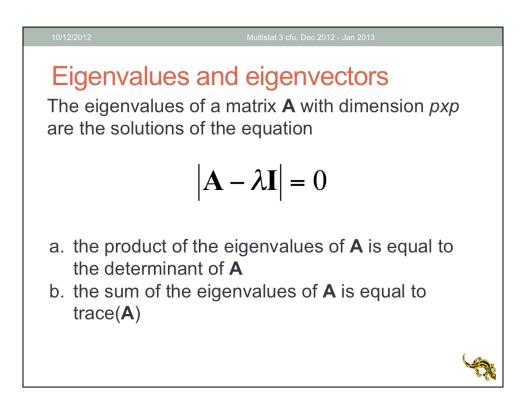
Multiplication of a mxn matrix by a nxn matrix can be used to obtain linear transformations of the first matrix. Examples are provided for Euclidean space in two dimensions. Check the article on linear transformations on wikipedia for further details.



This slide shows the difinition of Euclidean distance between two points with coordinates x and y (x and y are vectors).  $\theta$  è is the angle between the two vectors; In  $\cos \theta$  the vectors are divided by their length which is equivalent to normalizing them to unit length. If the two vectors are coincident then  $\cos \theta = 1$ ; if they are at right angle  $\cos \theta = 0$ . When **y=0**, **d** is also called the L2-norm (norm, for short) of the vector and is its length



Postmultiplication of a mxn matrix by a vector with dimension n linearly transforms the group of variables represented by the vector in a new space with n dimensions



The determinant of the equation is a polynomial of grade p. From: http://en.wikipedia.org/wiki/Matrix\_(mathematics) A number  $\lambda$  and a non-zero vector v satisfying

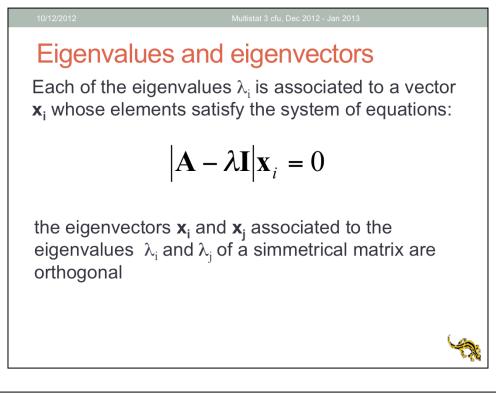
 $Av = \lambda v$ 

are called eigenvalue and eigenvector of A, respectively. The number  $\lambda$  is an eigenvalue of A if and only if A- $\lambda$ I is not invertible, which is equivalent to

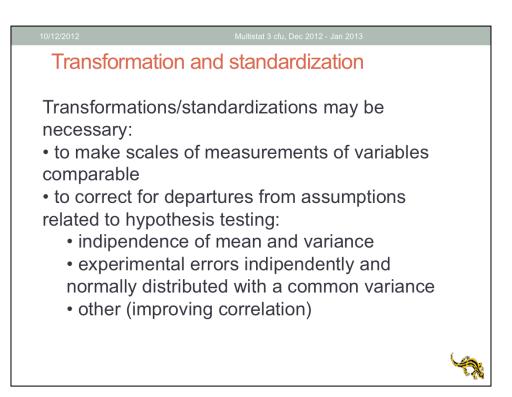
 $det(A - \lambda I) = 0$ 

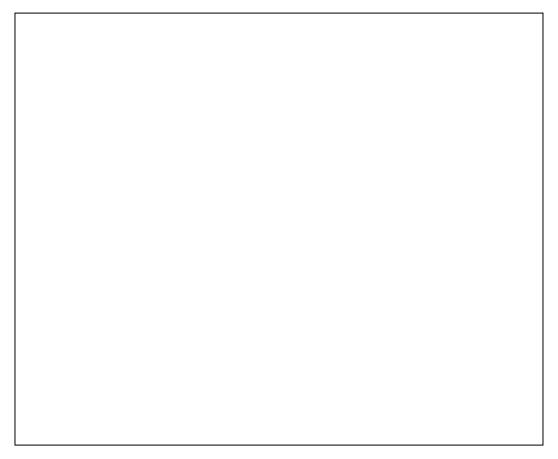
The function pA(t) = det(A-tI) is called the characteristic polynomial of A, the degree of this polynomial is n. Therefore pA(t) has at most n (possibly complex) different roots, i.e. eigenvalues of the matrix.

The trace of a square matrix is the sum of its diagonal entries. It equals the sum of its n eigenvalues.



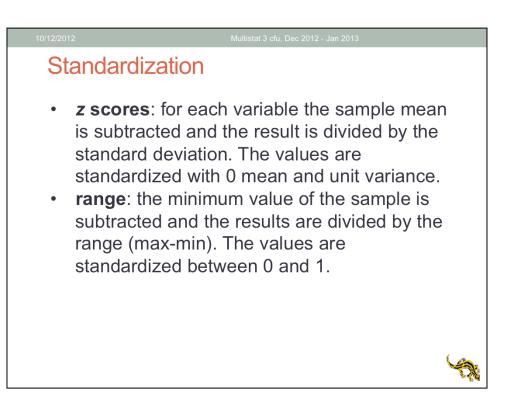




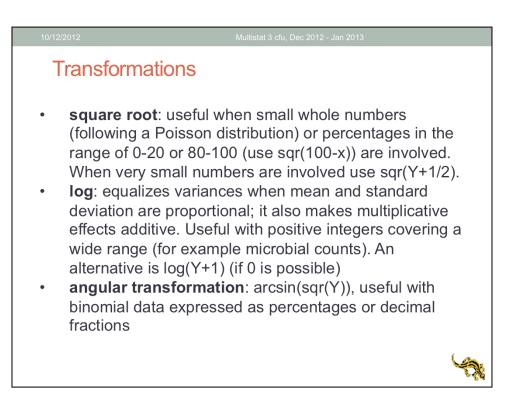


Method	Transformation(s)	Regression equation	Predicted value (ŷ
Standard linear regression	on None	$y = b_0 + b_1 x$	$\hat{y} = b_0 + b_1 x$
Exponential model	Dependent variable = log(y)	$log(y) = b_0 + b_1x$	$\hat{y} = 10^{b_0 + b_1 x}$
Quadratic model	Dependent variable = sqrt(y)	$sqrt(y) = b_0 + b_1x$	$\hat{y} = (b_0 + b_1 x)^2$
Reciprocal model	Dependent variable = 1/y	$1/y = b_0 + b_1 x$	$\hat{y} = 1 / (b_0 + b_1 x)$
Logarithmic model	Independent variable = log(x)	$y=b_0+b_1\log(x)$	$\hat{y} = b_0 + b_1 log(x)$
Power model	Dependent variable = log(y) Independent variable = log(x)	$log(y)=b_0+b_1log(x)$	$\hat{y}=10^{b_0+b_1log(x)}$

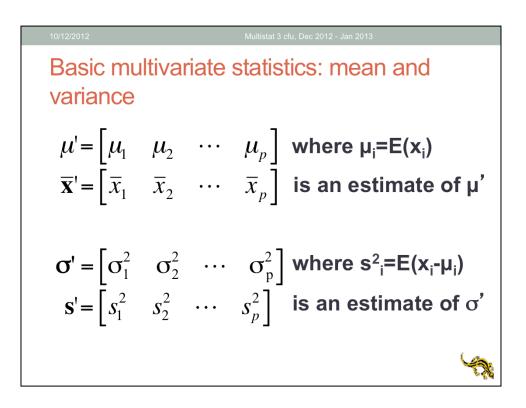
From stat trek web site



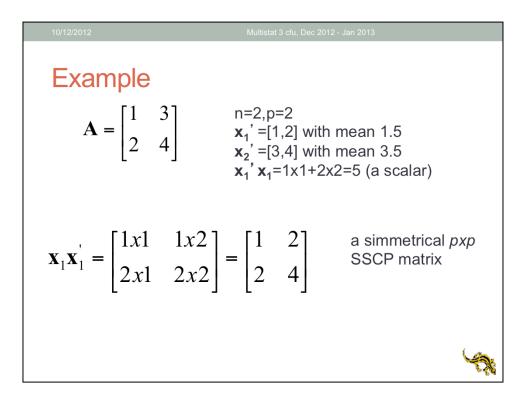


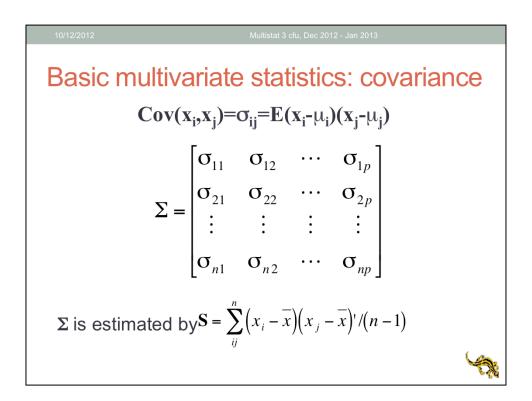




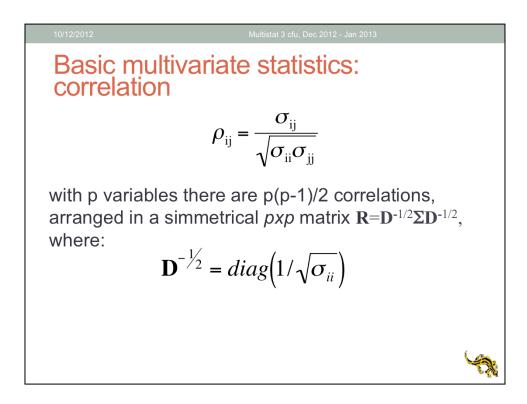


## Multistat2

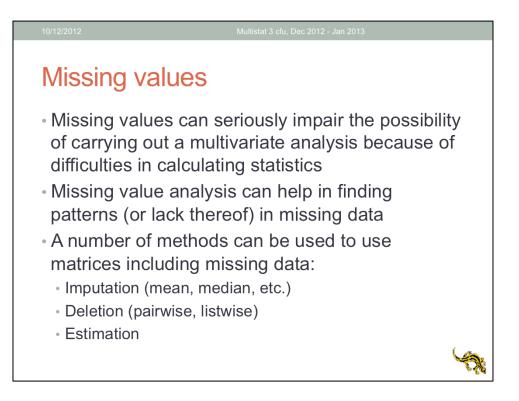




if i=j the covariance is the variance; with p variables a symmetrical pxp matrix is obtained and its diagonal are the variances (p variances) while there are p(p-1)/2 covariances. The matrix can also be called variance-covariance matrix. Covariance is highly sensitive to scale and therefore difficult to interpret



correlation is covariance standardized by the standard deviation of the variables. It varies between -1 and 1 and is a measure of linear relationship of the variables. With p variables there are p(p-1)/2 corelations arranged in a pxp matrix, with diagonal elements=1. Usually only the lower triangular matrix is used.



If a limited number of missing values is present it is oK to perform the analysis or to carry out imputation; if the number of missing values is high and especially if it is not at random the analysis should be used only to obtain preliminary information.