

Iterative Shepard operator of least squares thin-plate spline type

Andra Malina^a

^a Department of Mathematics, Babeş-Bolyai University Cluj-Napoca (Romania)

andra.malina@ubbcluj.ro

D. Shepard introduced in 1968 in [5] a very powerful method for approximating a given function f on a set of scattered data. A method for improving its accuracy was introduced by R. Franke and G. Nielson in [2].

T. Căţinaş and A. Malina introduced in [1] a new Shepard operator, based on the classical and the modified Shepard methods and the least-squares thin-plate spline function. The least squares thin-plate spline is defined for a point (x, y) and a set of nodes (x_i, y_i) as

$$F_i(x, y) = \sum_{j=1}^i C_j d_j^2 \log(d_j) + ax + by + c, \quad i = 1, \dots, N'$$

with $d_j = \sqrt{(x - x_j)^2 + (y - y_j)^2}$ and C_j, a, b, c found such that they minimize

$$E = \sum_{i=1}^{N'} [F_i(x_i, y_i) - f(x_i, y_i)]^2,$$

for two different values of N' , first with $N' = N$ interpolation nodes and second with $N' = k$ representative knot points, idea presented by J. McMahon in [4].

We propose an iterative modification of the Shepard operator of least squares thin-plate spline type, following an idea presented by A. Masjukov and V. Masjukov in [3]. The operator, denoted by u_L , is defined as

$$u_L(x, y) = \sum_{k=0}^K \sum_{j=1}^{N'} \left[u_{F_j}^{(k)} w((x - x_j, y - y_j)/\tau_k) / \sum_{p=1}^{N'} w((x_p - x_j, y_p - y_j)/\tau_k) \right],$$

where w is a continuously differentiable weight function with some particular properties, $u_{F_j}^{(k)}$ denotes the interpolation residuals at the k th step and τ_k is a scaling parameter.

References

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